

Introduction

Chapter 1

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Where do we come from? Where are we going?

$$\begin{aligned} \frac{\partial}{\partial a} \ln f_{a, \sigma^2}(\xi_1) &= \frac{(\xi_1 - a)}{\sigma^2} f_{a, \sigma^2}(\xi_1) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\xi_1 - a)^2}{2\sigma^2}\right) \\ \int_{\mathbb{R}_+} T(x) \cdot \frac{\partial}{\partial \theta} f(x, \theta) dx &= M\left(T(\xi) \cdot \frac{\partial}{\partial \theta} \ln L(\xi, \theta)\right) \int_{\mathbb{R}_+} T(x) f(x, \theta) dx \\ \int_{\mathbb{R}_+} T(x) \cdot \left(\frac{\partial}{\partial \theta} \ln L(x, \theta)\right) \cdot f(x, \theta) dx &= \int_{\mathbb{R}_+} T(x) \cdot \left(\frac{\partial}{\partial \theta} \frac{f(x, \theta)}{f(x, \theta)}\right) f(x, \theta) dx \end{aligned}$$

Mathematics



Engineering

John Tukey: "I wouldn't want to fly in a plane whose design depended on whether a function was Riemann or Lebesgue integrable."



Where do we come from? Where are we going?

$$\frac{\partial}{\partial a} \ln f_{a, \sigma^2}(\xi_1) = \frac{(\xi_1 - a)}{\sigma^2} f_{a, \sigma^2}(\xi_1) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\xi_1 - a)^2}{2\sigma^2}\right)$$

$$\int_{\mathbb{R}_+} T(x) \cdot \frac{\partial}{\partial \theta} f(x, \theta) dx = M\left(T(\xi) \cdot \frac{\partial}{\partial \theta} \ln L(\xi, \theta)\right) \int_{\mathbb{R}_+} T(x) f(x, \theta) dx$$

$$\int_{\mathbb{R}_+} T(x) \cdot \left(\frac{\partial}{\partial \theta} \ln L(x, \theta)\right) \cdot f(x, \theta) dx = \int_{\mathbb{R}_+} T(x) \cdot \left(\frac{\partial}{\partial \theta} \frac{f(x, \theta)}{f(x, \theta)}\right) f(x, \theta) dx$$

Mathematics



*Signals
and
Systems*



Engineering

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Bibliography- I

Basic Bibliography

- E. Gago-Ribas. Señales y Sistemas Escalares Unidimensionales de Variable Real. Vol. ST-I. {
- Signal Spaces
 - Transforms theory
 - Signals and Systems in CV
- A. V. Oppenheim, A. S. Willsky, I. T. Young. Signals and Systems (2nd. Ed.), Prentice-Hall International, 1997. {
- Signals and Systems
 - Transforms

Supplementary Bibliography

- A. V. Oppenheim, R. W. Schaffer, Digital Signal Processing, Pearson, 1975. {
- Signals and Systems in DV
 - Transforms in DV
- C. Gasquet and P. Witomski, Fourier analysis and applications, Springer, 1999. {
- Mathematical concerns
 - Distribution theory



Bibliography - II

Bibliography - Quizzes and Problems

E. Gago-Ribas. Señales y Sistemas Escalares Unidimensionales de Variable Real. Ejercicios Resueltos. Vol. ST-II. GR Editores, S.L., León, 2009.

- Signal spaces (CV)
- Signals and Systems (CV)
- Transforms (CV)
- Sampling

A. V. Oppenheim, A. S. Willsky, I. T. Young. Signals and Systems (2nd. Ed.), Prentice-Hall International, 1997.

- Everything (CV and DV)

The rest of the books in the bibliography also include a large number of problems, which are focused on the topics previously described.



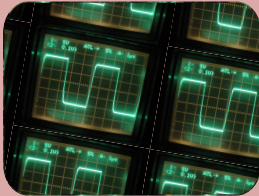
Resources

- Course bibliography (available in most university libraries)
- Virtual Campus
 - Slides/Notes
 - Lab. session notes and videos

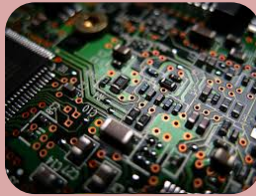


General overview

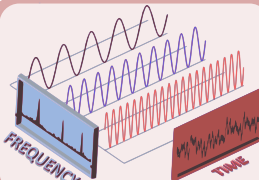
Signals



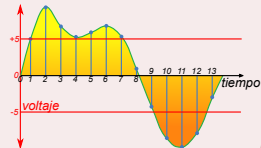
Systems



Transforms



Sampling



Syllabus

Part I: Introduction and General Analysis

Chapter 1: Introduction to the course

Chapter 2: Function (signal) spaces

Chapter 3: Operator spaces (systems)

Part II: Continuous-variable Signals and Systems

Chapter 4: Relevant starting signals

Chapter 5: Introduction to distribution theory

Chapter 6: Periodic signals: the Fourier series (FS) representation

Chapter 7: Aperiodic signals: The Fourier transform (FT)

Part III: Discrete-variable Signals and Systems

Chapter 8: Relevant starting signals

Chapter 9: Periodic signals: Fourier series (FS) representation of discrete-variable signals

Chapter 10: Aperiodic signals: the Fourier transform (FT) of discrete-variable signals

Part IV: Relation between continuous- and discrete-variable signals/systems

Chapter 11: Discrete- and Continuous-variable signals/systems

Appendixes: Complex-Variable Transforms

Appendix 1: Continuous variable: the Laplace transform

Appendix 2: Discrete variable: the z-transform

